

Certified Unsolvability in Classical Planning

1. Theoretical Foundations

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Introduction

Goal

learn about:

- different levels of correctness guarantees
- unsolvability certificates for classical planning
- [how to make your planner certifying](#)

Target Audience

- familiar with classical planning
- optional: planner developer

About us



Salomé



Gabi



Malte

Certifying Algorithms

Motivation

- ISP wants to build antenna towers for 5G.
- antenna supplier:
 - “You need **at least** x towers”
 - shows calculations with a tool, if using less than x towers tool says “unsolvable”
- ISP’s options:
 - blindly trust the tool
 - demand some form of **correctness guarantee** for their tool

Levels of Verification

How can we verify the correctness of an algorithm?

- ① **theoretical**: correctness proof in papers
- ② **implementation**:

verification method	verified inputs
unit test	some predesignated inputs
certifying algorithms	each input when it occurs
theorem provers	all possible inputs

- Unit tests are easy to do, but it is also easy to miss bugs.
- Theorem provers are very expensive but offer highest guarantee (tiny core which is checked very carefully).
- Certifying algorithms strike a balance between trust and effort.

Certifying Algorithms [McConnell et al. 2011]

“A certifying algorithm is an algorithm that produces, with each output, a certificate or witness (easy-to-verify proof) that the particular output has not been compromised by a bug.”

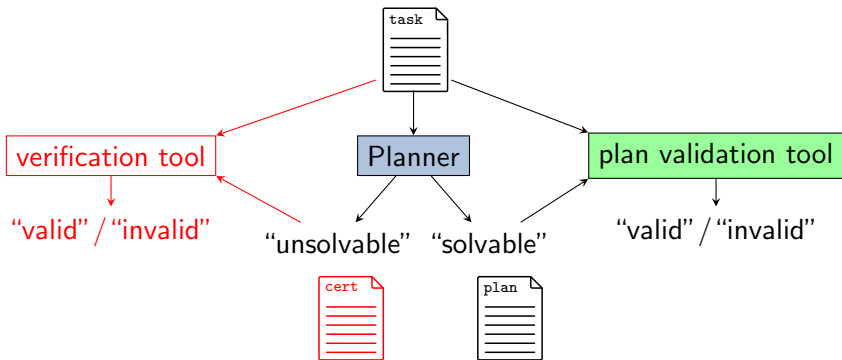
→ algorithm might still contain bug, but current output is correct

Example

Is CNF formula φ satisfiable?

- yes → provide satisfying assignment \mathcal{I}
- no → provide UNSAT certificate (resolution, DRAT proof...)

Certifying Algorithms in Planning



Guiding Properties

Soundness & Completeness

We can create a certificate for task Π iff Π is unsolvable.

Efficient Generation

Certificate creation incurs only polynomial overhead to the planner.

Efficient Verification

Certificate verification is at most polynomial in its size.

Generality

A wide variety of planning techniques can produce a certificate.

Quis custodiet ipsos custodes?

Certificate must be verified by a verifier. But what if the verifier has bugs?

- Verify the verifier!
- Verify the verifier-verifier!
- ...?
- At some point we need to trust something.

Good news: Verifiers are often simpler than the original algorithm.

→ [Verify the verifier with theorem provers.](#)

Example: A Formally Verified Validator for Classical Planning Problems and Solutions [Abdulaziz & Lammich, 2018]

Proof Systems

Natural Deduction

- Proof systems are built on **axioms** and **inference rules**.
 - axioms: tautology ($A \vee \neg A$)
 - inference rules: conclusion based on premises (if $A \wedge B$ then A)
- **Hilbert-style systems** try to express as much as possible in axioms.
- **Natural deduction** in contrast focuses on inference rules.
 - first proposed by Gerhard Genzen [Genzen 1935]
 - should more closely reflect our natural way of reasoning

The proof system presented here uses the natural deduction style.

Inference Rules

Inference rule

An inference rule \mathcal{I} takes premises A_1, \dots, A_n and concludes B :

$$\frac{A_1 \quad \dots \quad A_n}{B} \mathcal{I}$$

- Rules use placeholder variables and are **universally true** for all instantiations.
- The correctness of rules can be shown in two ways:
 - within the proof system using existing rules, or
 - outside of the proof system.

→ Once proven correct, we can use rules purely **syntactically**.
- **Axioms** are rules with no premises.
- Rules can also use and discard **assumptions**: For example, if under assumption A we can prove B , we have shown $A \rightarrow B$.

Example Proof System

Example

Inference Rules:

$$\frac{\star \quad \diamond}{\square} \mathbf{A} \quad \frac{}{\diamond} \mathbf{B} \quad \frac{\diamond}{\star} \mathbf{C} \quad \frac{\square \quad \star \quad \diamond}{\circ} \mathbf{D}$$

Show ○:

statement justification

Example Proof System

Example

Inference Rules:

$$\frac{\star \quad \diamond}{\square} \mathbf{A} \quad \frac{}{\diamond} \mathbf{B} \quad \frac{\diamond}{\star} \mathbf{C} \quad \frac{\square \quad \star \quad \diamond}{\circ} \mathbf{D}$$

Show ○:

#	statement	justification
(1)	◇	from B

Example Proof System

Example

Inference Rules:

$$\frac{\star \quad \diamond}{\square} \mathbf{A} \quad \frac{}{\diamond} \mathbf{B} \quad \frac{\diamond}{\star} \mathbf{C} \quad \frac{\square}{\circ} \frac{\star \quad \diamond}{\quad} \mathbf{D}$$

Show ○:

#	statement	justification
(1)	◇	from B
(2)	★	from C with (1)

Example Proof System

Example

Inference Rules:

$$\frac{\star \quad \diamond}{\square} \mathbf{A} \quad \frac{}{\diamond} \mathbf{B} \quad \frac{\diamond}{\star} \mathbf{C} \quad \frac{\square \quad \star \quad \diamond}{\circ} \mathbf{D}$$

Show ○:

#	statement	justification
(1)	◇	from B
(2)	★	from C with (1)
(3)	□	from A with (2) and (1)

Example Proof System

Example

Inference Rules:

$$\frac{\star \quad \diamond}{\square} \mathbf{A} \quad \frac{}{\diamond} \mathbf{B} \quad \frac{\diamond}{\star} \mathbf{C} \quad \frac{\square \quad \star \quad \diamond}{\circ} \mathbf{D}$$

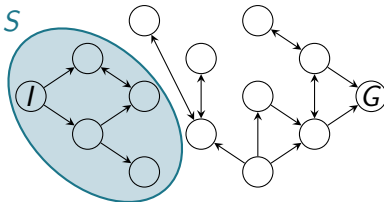
Show ○:

#	statement	justification
(1)	◇	from B
(2)	★	from C with (1)
(3)	□	from A with (2) and (1)
(4)	○	from D with (3), (2) and (1)

Unsolvability Proof System

First Certificate Attempt

How can we show that a planning task is unsolvable?



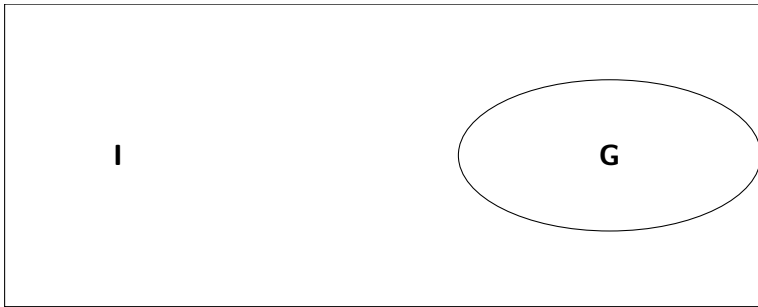
Inductive Certificate [E et al 2017]

An inductive certificate for a STRIPS planning task

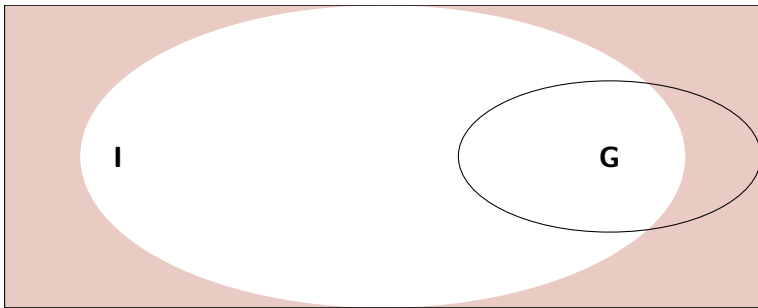
$\Pi = \langle \mathbf{V}, \mathbf{A}, \mathbf{I}, \mathbf{G} \rangle$ is a set of states S with the following properties:

- $\mathbf{I} \in S$
- S contains no goal state
- $S[\mathbf{A}] \subseteq S$, where $S[\mathbf{A}] = \{s' \mid s[a] = s' \text{ for some } a \in \mathbf{A}\}$

How Planners Show Unsolvability

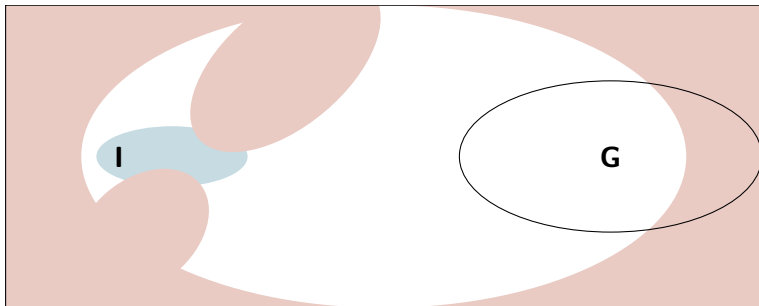


How Planners Show Unsolvability



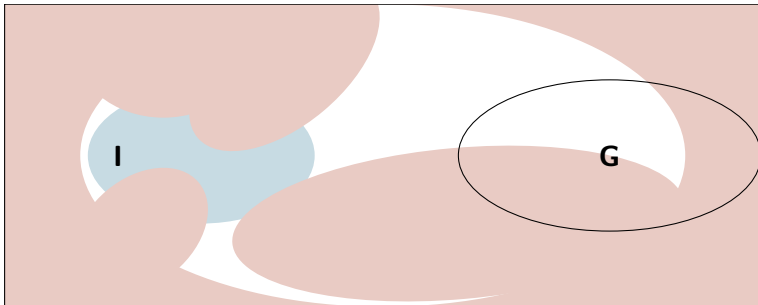
preprocessing

How Planners Show Unsolvability



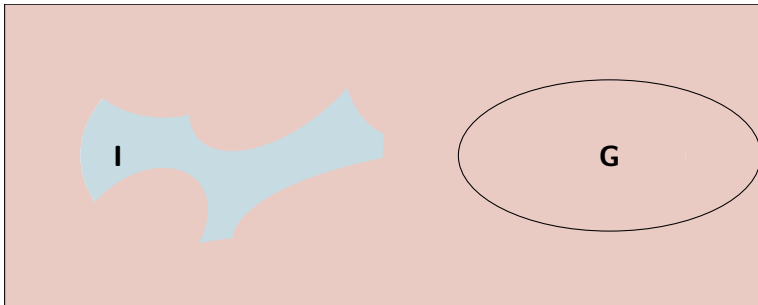
heuristic search with dead-end pruning

How Planners Show Unsolvability



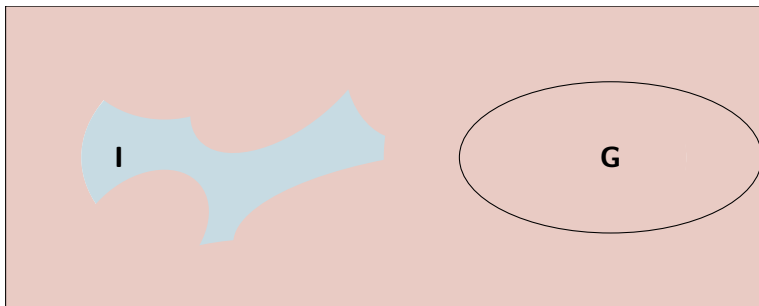
heuristic search with dead-end pruning

How Planners Show Unsolvability



heuristic search with dead-end pruning

How Planners Show Unsolvability



- Uninteresting search space areas get pruned **incrementally**
 - Later pruning steps can use knowledge from previous ones.
 - Distilling these steps into a singular argument is difficult.
- Proof systems can capture this type of incremental reasoning.

Proof System Objects

- state sets S represented as
 - BDD
 - (dual)-Horn formula
 - 2CNF formula
 - explicit enumeration
 - ...
- action sets A represented as ID enumeration

Types of Knowledge

Dead State

A state s is dead if no plan traverses s , i.e. there is no plan $\pi = \langle a_1, \dots, a_n \rangle$ and $1 \leq i \leq n$ with $s = \mathbb{I}[a_1] \dots [a_i]$.

→ captures idea of pruned states (in both directions)

statements in the proof system:

- S dead (all $s \in S$ dead)
- $E \sqsubseteq E'$ (where E and E' are sets of states or actions)
- unsolvable

Inference Rules - Showing Deadness

Empty set **D**ead

$$\frac{}{\emptyset \text{ dead}} \text{ED}$$

Union **D**ead

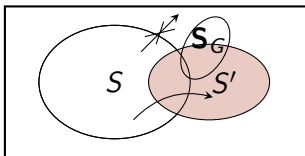
$$\frac{S \text{ dead} \quad S' \text{ dead}}{S \cup S' \text{ dead}} \text{UD}$$

Subset **D**ead

$$\frac{S' \text{ dead} \quad S \sqsubseteq S'}{S \text{ dead}} \text{SD}$$

Inference Rules - Showing Deadness

Progression Goal

$$\frac{S[\mathbf{A}] \sqsubseteq S \cup S' \quad S' \text{ dead} \quad S \cap \mathbf{S}_G \text{ dead}}{S \text{ dead}} \quad \mathbf{PG}$$


Inference Rules - Showing Deadness

$$\frac{\text{Progression Goal} \quad S[\mathbf{A}] \sqsubseteq S \cup S' \quad S' \text{ dead} \quad S \cap \mathbf{S}_G \text{ dead}}{S \text{ dead}} \text{PG}$$

$$\frac{\text{Progression Initial} \quad S[\mathbf{A}] \sqsubseteq S \cup S' \quad S' \text{ dead} \quad \{\mathbf{I}\} \sqsubseteq S}{\bar{S} \text{ dead}} \text{PI}$$

$$\frac{\text{Regression Goal} \quad [\mathbf{A}]S \sqsubseteq S \cup S' \quad S' \text{ dead} \quad \bar{S} \cap \mathbf{S}_G \text{ dead}}{\bar{S} \text{ dead}} \text{RG}$$

$$\frac{\text{Regression Initial} \quad [\mathbf{A}]S \sqsubseteq S \cup S' \quad S' \text{ dead} \quad \{\mathbf{I}\} \sqsubseteq \bar{S}}{S \text{ dead}} \text{RI}$$

Inference Rules - Showing Unsolvability

Conclusion **I**nitial

$$\frac{\{\mathbf{I}\} \text{ dead}}{\text{unsolvable}} \mathbf{CI}$$

Conclusion **G**oal

$$\frac{\mathbf{S}_G \text{ dead}}{\text{unsolvable}} \mathbf{CG}$$

Inference Rules - Set Theory

Union Left

$$\frac{}{E \subseteq (E' \cup E)} \text{UL}$$

Intersection Right

$$\frac{}{(E \cap E') \subseteq E} \text{IR}$$

Subset Union

$$\frac{E \subseteq E'' \quad E' \subseteq E''}{(E \cup E') \subseteq E''} \text{SU}$$

Subset Intersection

$$\frac{E \subseteq E' \quad E \subseteq E''}{E \subseteq (E' \cap E'')} \text{SI}$$

Subset Transitivity

$$\frac{E \subseteq E' \quad E' \subseteq E''}{E \subseteq E''} \text{ST}$$

...

Inference Rules - Progression and Regression

Action **U**nion

$$\frac{S[A] \sqsubseteq S' \quad S[A'] \sqsubseteq S'}{S[A \cup A'] \sqsubseteq S'} \quad \mathbf{AU}$$

Progression **T**ransitivity

$$\frac{S[A] \sqsubseteq S'' \quad S' \sqsubseteq S}{S'[A] \sqsubseteq S''} \quad \mathbf{PT}$$

Progression to **R**egression

$$\frac{S[A] \sqsubseteq S'}{[A]\overline{S'} \sqsubseteq \overline{S}} \quad \mathbf{PR}$$

...

Is this enough?

How can we show $S[A] \subseteq S$ or similar statements?

- depends on planning task and contents of S
- requires **semantic** analysis
- set theory rules only syntactical

→ new source of information: **basic statements**

Basic Statements

$$\mathbf{B1} \quad \bigcap L_R \subseteq \bigcup L'_R$$

$$\mathbf{B2} \quad (\bigcap X_R)[A] \cap \bigcap L_R \subseteq \bigcup L'_R$$

$$\mathbf{B3} \quad [A](\bigcap X_R) \cap \bigcap L_R \subseteq \bigcup L'_R$$

$$\mathbf{B4} \quad L_R \subseteq L'_R$$

$$\mathbf{B5} \quad A \subseteq A'$$

X_R state set variable
(represented by formalism **R**)

L_R state set literal
(either X_R or $\overline{X_R}$)

A action set

- In **B1-B3** all sets must be represented by the **same** formalism.
- Unions and intersections are **bounded**.
- We only support pro-/regression for set **variables**.
- **B4** enables us to **mix** formalisms.

Soundness and Completeness

Given a STRIPS planning tasks $\Pi = \langle \mathbf{V}, \mathbf{A}, \mathbf{I}, \mathbf{G} \rangle$, there is a proof in the proof system for Π iff Π is unsolvable.

Proof

Soundness: This follows from the correctness of the inference rules and basic statements.

Completeness: Consider \mathcal{R}^Π , the set of states reachable from \mathbf{I} .

#	statement	justification
(1)	\emptyset dead	ED
(2)	$\mathcal{R}^\Pi[\mathbf{A}] \subseteq \mathcal{R}^\Pi \cup \emptyset$	B2
(3)	$\mathcal{R}^\Pi \cap \mathbf{S}_G \subseteq \emptyset$	B1
(4)	$\mathcal{R}^\Pi \cap \mathbf{S}_G$ dead	SD with (1) and (3)
(5)	\mathcal{R}^Π dead	PG with (2), (1) and (4)
(6)	$\{\mathbf{I}\} \subseteq \mathcal{R}^\Pi$	B1
(7)	$\{\mathbf{I}\}$ dead	SD with (5) and (6)
(8)	unsolvable	CI with (7)

Efficient Verification

Verifying Statements

The verifier needs to verify each step of the proof.

- inference rules
 - universally true
 - check if rule is applied corretly (**syntax**)
 - easy to verify
- basic statements
 - sets must be interpreted (**semantic**)
 - depends on set representation formalism

Formalisms & Operations

How can we analyze whether basic statements can be verified efficiently?

- 1 check each formalism separately
- 2 check what **operations** a formalism **R** must support
 - **SE** (sentential entailment): Given **R**-formulas φ and ψ , test whether $\varphi \models \psi$.
 - **\wedge BC** (bounded conjunction): Given **R**-formulas φ and ψ , construct an **R**-formula representing $\varphi \wedge \psi$.
 - **toCNF** (transform to CNF): Given **R**-formula φ , construct a CNF formula that is equivalent to φ .
 - ... [Darwiche & Marques 2002]

Efficient Verification of **B1**

To verify $\bigcap X_R \subseteq \bigcup X'_R$ efficiently **R** must efficiently support:

	$ \bigcap X_R = 0$	$ \bigcap X_R = 1$	$ \bigcap X_R > 1$
$ \bigcup X'_R = 0$		CO	CO, $\wedge BC$ toDNF
$ \bigcup X'_R = 1$	VA	SE	SE, $\wedge BC$ toDNF, IM
$ \bigcup X'_R > 1$	VA, $\vee BC$ toCNF	SE, $\vee BC$ toCNF, CE	SE, $\wedge BC, \vee BC$ toDNF, IM, $\vee BC$ toCNF, CE, $\wedge BC$

- multiple rows indicate different possible options
- for **B1**: move negated literals to the “correct” side

Efficient Verification of **B1** - Example

	$ \bigcap X_R = 0$	$ \bigcap X_R = 1$	$ \bigcap X_R > 1$
$ \bigcup X'_R = 0$		CO	CO, $\wedge BC$ toDNF
$ \bigcup X'_R = 1$	VA	SE	SE, $\wedge BC$ toDNF, IM
$ \bigcup X'_R > 1$	VA, $\vee BC$ toCNF	SE, $\vee BC$ toCNF, CE	SE, $\wedge BC$, $\vee BC$ toDNF, IM, $\vee BC$ toCNF, CE, $\wedge BC$

Example

For sets S_1 to S_5 (all represented with **R**), the statement $S_1 \cap \overline{S_2} \subseteq S_3 \cup S_4 \cup S_5$ can be verified efficiently iff **R** supports

- **SE** (sentential entailment) and $\vee BC$ (bounded disjunction), or
- **toCNF** (transform to CNF) and **CE** (clausal entailment).

Concrete Formalisms

What do BDDs, (dual-)Horn formulas, 2CNF formulas and explicit enumeration support?

- Basic statements **B1-B3** are fully supported by all formalisms.
- Basic statement **B4** between those formalisms is supported in most cases with the following exceptions:
 - $\varphi_{\mathbf{R}} \models \neg\psi'_{\mathbf{R}'}$ where **R** and **R'** are a combination of BDD, (dual-)Horn and 2CNF
 - $\varphi_{(\text{dual-})\text{Horn}/2\text{CNF}} \models \psi_{\text{BDD}}$